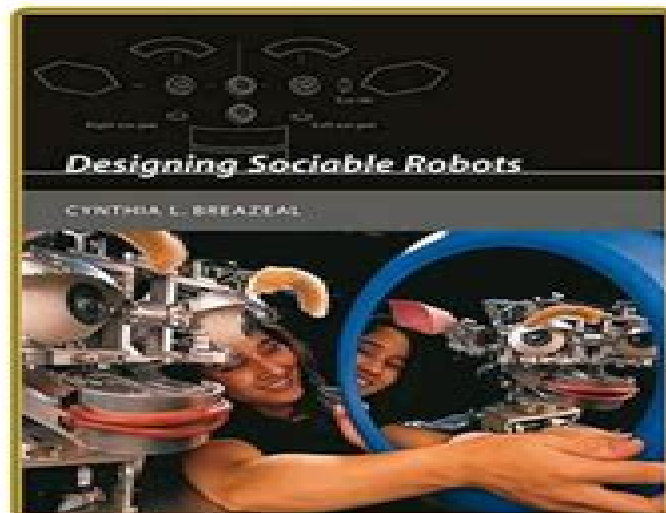


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Designing Sociable Robots Intelligent Robotics And Autonomous Agents Series

Fahri Özsungur, Fevziye Bekar



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Designing Sociable Robots Cynthia Breazeal, 2004-08-20 Cynthia Breazeal here presents her vision of the sociable robot of the future a synthetic creature and not merely a sophisticated tool A sociable robot will be able to understand us to communicate and interact with us to learn from us and grow with us It will be socially intelligent in a humanlike way Eventually sociable robots will assist us in our daily lives as collaborators and companions Because the most successful sociable robots will share our social characteristics the effort to make sociable robots is also a means for exploring human social intelligence and even what it means to be human Breazeal defines the key components of social intelligence for these machines and offers a framework and set of design issues for their realization Much of the book focuses on a nascent sociable robot she designed named Kismet Breazeal offers a concrete implementation for Kismet incorporating insights from the scientific study of animals and people as well as from artistic disciplines such as classical animation This blending of science engineering and art creates a lifelike quality that encourages people to treat Kismet as a social creature rather than just a machine The book includes a CD ROM that shows Kismet in action

Designing Sociable Robots Cynthia L. Breazeal, 2002 A blueprint for the design of sociable robots as well as the story of Kismet a nascent example

Social Robots Marco Nørskov, 2017-07-05 Social robotics is a cutting edge research area gathering researchers and stakeholders from various disciplines and organizations The transformational potential that these machines in the form of for example caregiving entertainment or partner robots pose to our societies and to us as individuals seems to be limited by our technical limitations and phantasy alone This collection contributes to the field of social robotics by exploring its boundaries from a philosophically informed standpoint It constructively outlines central potentials and challenges and thereby also provides a stable fundament for further research of empirical qualitative or methodological nature

Social Robotics Miguel A. Salichs, Shuzhi Sam Ge, Emilia Ivanova Barakova, John-John Cabibihan, Alan R. Wagner, Álvaro Castro-González, Hongsheng He, 2019-11-21 This book constitutes the refereed proceedings of the 11th International Conference on Social Robotics ICSR 2019 held in Madrid Spain in November 2019 The 69 full papers presented were carefully reviewed and selected from 92 submissions The theme of the 2018 conference is Friendly Robotics The papers focus on the following topics perceptions and expectations of social robots cognition and social values for social robots verbal interaction with social robots social cues and design of social robots emotional and expressive interaction with social robots collaborative SR and SR at the workplace game approaches and applications to HRI applications in health domain robots at home and at public spaces robots in education technical innovations in social robotics and privacy and safety of the social robots

Advances in Service and Industrial Robotics Kosta Jovanović, Aleksandar Rodić, Mirko Raković, 2025-09-01 This book presents the Proceedings of the 34th International Conference on Robotics in Alpe Adria Danube Region RAAD held in Belgrade Serbia on June 18 20 2025 It gathers contributions by researchers from multiple countries on all major areas of robotic research development and

innovation as well as new applications and current trends The topics include perception and learning medical robotics and biomechanics industrial robots and education kinematics and dynamics motion planning and control service robotics and applications mobile robots and innovative robot design etc Given its scope the book offers a source of information and inspiration for researchers seeking to improve their work and gather new ideas for future developments Cognitive Robotics Angelo Cangelosi, Minoru Asada, 2022-05-17 The current state of the art in cognitive robotics covering the challenges of building AI powered intelligent robots inspired by natural cognitive systems A novel approach to building AI powered intelligent robots takes inspiration from the way natural cognitive systems in humans animals and biological systems develop intelligence by exploiting the full power of interactions between body and brain the physical and social environment in which they live and phylogenetic developmental and learning dynamics This volume reports on the current state of the art in cognitive robotics offering the first comprehensive coverage of building robots inspired by natural cognitive systems Contributors first provide a systematic definition of cognitive robotics and a history of developments in the field They describe in detail five main approaches developmental neuro evolutionary swarm and soft robotics They go on to consider methodologies and concepts treating topics that include commonly used cognitive robotics platforms and robot simulators biomimetic skin as an example of a hardware based approach machine learning methods and cognitive architecture Finally they cover the behavioral and cognitive capabilities of a variety of models experiments and applications looking at issues that range from intrinsic motivation and perception to robot consciousness Cognitive Robotics is aimed at an interdisciplinary audience balancing technical details and examples for the computational reader with theoretical and experimental findings for the empirical scientist **Spirituality Management in the Workplace** Fahri Özsungur, Fevziye Bekar, 2023-12-14 The experts here provide conceptual frameworks and guidance by examining the subject in the light of current developments at multiple levels of analysis individual organizational cultural and in leadership Spirituality in the workplace considers employees as a whole in spirit body and mind Multiagent Systems, second edition Gerhard Weiss, 2013-03-08 The new edition of an introduction to multiagent systems that captures the state of the art in both theory and practice suitable as textbook or reference Multiagent systems are made up of multiple interacting intelligent agents computational entities to some degree autonomous and able to cooperate compete communicate act flexibly and exercise control over their behavior within the frame of their objectives They are the enabling technology for a wide range of advanced applications relying on distributed and parallel processing of data information and knowledge relevant in domains ranging from industrial manufacturing to e commerce to health care This book offers a state of the art introduction to multiagent systems covering the field in both breadth and depth and treating both theory and practice It is suitable for classroom use or independent study This second edition has been completely revised capturing the tremendous developments in multiagent systems since the first edition appeared in 1999 Sixteen of the book s seventeen chapters were written for this edition all chapters are by

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